Printed Pages—3	TME404
(Following Paper ID and Roll No. to be fil	led in your Answer Book)
PAPER ID : 4082 Roll No.	
B.Tech.	
(SEM. IV) THEORY EXAMIN	VATION 2010-11
MEASUREMENTS, METROLOG	GY AND CONTROL
Time : 3 Hours	Total Marks : 100
Note: (1) Attempt all questions.	
(2) All questions carry equal ma	rks
(3) Assume any data if necessar	ry.
1. Attempt any two parts :	$(10 \times 2 = 20)$
(a) Define the following charac	teristics of a measuring
instrument :	
(i) Range	and the second second
(ii) Drift	E La Contra C
(iii) Sensitivity	A 4 10
(iv) Hysteresis	
(b) Discuss the following consideration	ion with respect to selection
of a transducer.	
(i) Mechnical suitability	
(ii) Electrical suitability.	
(c) Name the various method develo	ped for signal transmission.
Discuss any two of them in deta	ail.

2. Attempt any two parts :

(a) With a neat sketch describe the construction and working of a hydraulic load cell.

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 $(10 \times 2 = 20)$

- (b) Why temperature compensation is required in strain gauges ? Name different methods for temperature compensation and explain working of any one of them.
- (c) Explain the construction and working of bourdon tube pressure transducer with the help of suitable figure.
- 3. Attempt any two parts :

 $(10 \times 2 = 20)$

- (a) Explain the working of sigma comparator with a neat sketch.
- (b) Write the functions of basic units of comparator. Discuss
 various merits and demerits of mechanical comparators.
- (c) Differentiate between the following :
 - (i) Standard and limit gauges
 - (ii) Fixed and Adjustable gauge.
- 4. Attempt any two parts :

 $(10 \times 2 = 20)$

- (a) Describe the constructional features of tool maker microscope. Discuss its application in metrology with suitable example.
- (b) What is "macro geometrical errors"? Discuss the working of spirit level to check straightness of a horizontal surface.
- (c) Explain the principle of optical flat with neat sketch for measurement of flatness.

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5. Attempt any two parts :

 $(10 \times 2 = 20)$

- (a) Write application of following controller components.
 - (i) Sensor
 - (ii) Amplification
 - (iii) Actuators
- (b) Discuss the advantages and limitations of following
 - (i) Hydraulic controller
 - (ii) Pneumatic controller
- (c) What do you understand by transfer function ? Derive the expression for transfer function for spring mass damper system. (Assume suitable data and condition if required)