



(Following Paper ID and Roll No. to be filled in your Answer Book)

PAPER ID : 100410

Roll No.

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B. Tech.

**(SEM. IV) THEORY EXAMINATION, 2014-15
GEO-INFORMATICS**

Time : 3 Hours]

[Total Marks : 100

Note : Attempt all the questions.

1 Attempt any TWO questions : 2×10=20

- (a) Explain what is relief displacement and how is it calculated ? The distance from the principal point to an image on a photograph is 6.44 cm and the elevation of the object above datum is 250m what is the relief displacement of the point if datum is 1/10000 and focal length is 20cm.
- (b) Describe any **TWO** with a neat sketch :
 - (i) Parallax bar
 - (ii) Mirror stereoscope
- (c) Why overlapping is necessary ? The scale of aerial photograph is 1cm=160m and the size of photograph is 20 cm*20cm. If the longitudinal lap is 65% and side lap 35%. Determine the no. of photographs required to cover an area 348 sq. km.

2 Attempt any TWO questions.

2×10=20

- (a) Differentiate the following :
- (i) Geostationary and sun-synchronous satellites.
 - (ii) Ideal and real remote sensing system
- (b) Explain the general process involved in electromagnetic remote sensing. Differentiate between active and passive remote sensing systems, under what condition each is preferable.
- (c) In remote sensing what is multiconcept ? Explain its use in various applications.

3 Attempt any TWO questions.

2×10=20

- (a) Describe in brief the radiometric and geometric corrections which are required for rectification of satellite image.
- (b) Differentiate between restoration and enhancement of remote sensing images. List any four image enhancing operation and explain any one of them.
- (c) Explain land use land cover classification system. Also describe one method of supervised classification of remote sensing image.

4 Attempt any TWO questions.

2×10=20

- (a) Describe advantages and disadvantages of vector data structure and raster data structure.
- (b) What is GIS and its component ? Explain.
- (c) What do you understand by spatial data ? How is the spatial relationship represented ?

5 Attempt any TWO questions.

2×10=20

- (a) Describe differential GPS and its advantages and functioning.
- (b) How many satellite must be visible in order to determine 3D position correctly. Discuss how the distance from the satellite to the GPS receiver is determined with a suitable sketch.
- (c) Explain following : (any two)
 - (i) Global navigation satellite system.
 - (ii) Kinematic GPS.
 - (iii) Principle of data encoding.