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(Following Paper ID and Roll No. to be filled in your Answer Book)			
Pape	r ID : 121521	Roll No.	
B.Tech.			
(SEM. V) THEORY EXAMINATION, 2015-16			
ELECTROMECHANICAL ENERGY CONVERSION-II			
[Time:3 hours]			[MaximumMarks:100
SECTION-A			
Note: Attempt <u>all</u> parts. All parts carry equal marks. Wranswer of each part in short. $(2\times10=2)$			
(a)	Why the power factor of the lightly loaded induction mechine is quite low?		
(b)	What do you understand by the term cogging?		
(c)	Calculate the speed in rpm of a 6 pole induction motor which has a slop of 6% at full load with a supply frequency of 50 Hz. What will be the speed of a 4 pole alternator supplying the motor?		
(d)	Give application areas of the cylindrical and salient pole type synchronous machine.		
(e)	Why in case of three phase synchronous machine, the		
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armature windings put on stator and field windings put on rotor wheras in case of DC machine, the armature windings put on rotor and field windings put on stator poles?

- (f) Draw the V-curves and inverted V-Curves at different loading conditions of synchronous motor.
- (g) Define slip. Why the induction motor can't run at synchronous speed?
- (h) What are the reasons for the Hunting phenomenon in synchronous machines?
- (i) State some important application of the stepper motors.
- (j) How will you reverse the direction of rotation of the single phase Induction motor?

## **SECTION-B**

Note: Attempt any five questions from this sections.

 $(10 \times 5 = 50)$ 

Q2. Shor that in a 3 phase induction motor.

$$\frac{\tau \max}{\tau fl} = \frac{1}{2} \frac{\beta^2 + sfl^2}{\beta sfl}$$

$$where \beta = \frac{R_2}{X_{20}}$$

Q3. A 3-phase, 400 V, 50 Hz induction motor take the power input of 35 kW at its full load speed of 890 rpm. The stator losses are 1 kW and friction and windage losses are 1.5 kW. Calculate (i)slip, (ii)Rotor ohmic loss(iii) Shaft power(iv) Shaft Torque(v) Efficiency

- Q4. From the first principles derive the equivalent circuit of a three phase induction motro. How the mechanical load is separated from rotor copper loss in the quuivalent circuit.
- Q5. Explain the phenomenon of armature reaction when alternator is delivering a load current at purely leading and purely lagging power factor. Also derive the eMF equation of an alternator.
- Q6. Derive Torque, Mechanical Power and rotor output equations of a three phase induction motor connected from AC mains.
- Q7. Define the term voltage regulation, for the synchronous generator. Determine the voltage regulation of a 2000 V, single phase alternator giving current of 100 A at (i) 0.8 pf leading and 0.707 pg lagging. Use the test data given below: Full load current of 100A is produced on short circuit by a field excitation of 2.5A. An EMF of 500 V is generated on open circuit by the same excitation. The armature resistance being 0.8Ω
- Q8. Why single phase induction motor is not self started? discuss the different methods of starting a 1-phase Induction motor.
- Q9. A 230 V, 50Hz, 4-pole single-phase induction motor has the following equivalent circuit impedances:

$$R_{1m} = 2.2 \text{ ohm}, X_{1m} = 3.1 \text{ ohm}, R2' = 4.5 \text{ ohm},$$
  
 $X2' = 2.6 \text{ ohm}, X_{M} = 80 \text{ ohm}$ 

Friction, windage and core loss=40W.

For a slip of 0.03 pu, calculate:

- i. Input current
- ii. Power factor
- iii. Developed power
- iv. Output power
- v. Efficiency

## SECTION-C

Note: Attempt any two parts of the following:

 $(2 \times 15 = 30)$ 

- Q10. (a) State the necessary conditions for parallel operation of alternators. Discuss two bright and one dark lamp method of synchronizing alternators.
  - (b) A 5000kVA, 10000V, 1500rpm, 50 Hz alternator runs in parallel with other machine. Its synchronous reactance is 20% Find for (a) No-Load,(b)Full load at p.f. 0.8 Lagging, synchronizing power per unit mechanical angle of face displacement and calculate the synchronizing torque if mechanical displacement is 0.5 degree.
- Q11. (a) What are the effects of space harmonics in 3 phase induction motors?
  - (b) The standsstill impedances of outer and inner cages of a double cage induction motors are  $(C+j1.2)\Omega$  and  $(0.5+j3.5)\Omega$  respectively. Determine the slip at which the 2 cages develop equal torques.

- Q12. Discuss the construction detail & working Principle fo the following:
  - a) Stepper Motors
  - b) Universal Motors
  - c) Shaded Pole type Induction Motor.

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