



Printed Pages : 3

TCS-041

(Following Paper ID and Roll No. to be filled in your Answer Book)

PAPER ID : 0149

Roll No.

## B. Tech.

(SEM. VIII) EXAMINATION, 2007-08  
REAL TIME SYSTEM

Time : 3 Hours]

[Total Marks : 100

Notes : Attempt **all** questions.

1 Attempt any **four** parts :

- (a) Differentiate between soft and hard real time systems with suitable examples.
- (b) Differentiate between aperiodic and sporadic jobs? Explain the general strategy to handle sporadic jobs.
- (c) Explain why predictability is considered as an important requirement of a real time system? How this requirement can be enforced?
- (d) What are real time tasks? Distinguish between a Real Time task and a non real time task.
- (e) What is an embedded system? Explain with a suitable example.
- (f) Define performability with a suitable example.



2 Attempt any **two** parts :

- (a) What is rate monotonic (RM) scheduling algorithm?  
Discuss its assumptions.

If there are two tasks,  $T_1$  and  $T_2$  and

$$\frac{e_1}{p_1} + \frac{e_2}{p_2} \leq 2(\sqrt{2} - 1)$$

then show that the tasks are RM-schedulable

- (b) Differentiate between :
- (i) Offline and online scheduling algorithms.
  - (ii) Feasibility and optimality
  - (iii) Fixed priority and dynamic priority
  - (iv) Priority driven and clock driven system
  - (v) Real time systems and general purpose systems.
- (c) Discuss the general structure of cyclic schedules. How is average response time of aperiodic jobs improved?

3 Attempt any **two** parts :

- (a) Define Basic Priority - Inheritance protocol and explain its working by taking a suitable example.
- (b) Differentiate between the priority Inheritance and priority-ceiling protocols. Explain how deadlock avoidance is done by priority-ceiling protocol.
- (c) A system contains the following four periodic tasks. The tasks are scheduled by the rate-monotonic algorithm and the priority ceiling protocol.
- $T_1 = (3, 0.75)$   $b_1 = 0.9$   
 $T_2 = (3.5, 1.5)$   $b_2 = 0.75$   
 $T_3 = (6, 0.6)$   $b_3 = 1.0$   
 $T_4 = (10, 1)$
- $B_1$  is the blocking time of  $T_i$ . Are the tasks schedulable? Explain your answer.



4 Attempt any **two** parts:

- (a) Differentiate between
- Multiprocessor system and distributed system
  - Identical and Heterogeneous processors
  - Local and Remote resources
  - RMFF and RMST algorithms
  - Predictability and validation.
- (b) Describe Multiprocessor priority ceiling protocol with a suitable example.
- (c) Consider a processor  $P$  in an end-to-end system that uses the release-guard protocol in synchronize subtasks on different processors. There are only two subtasks  $T_{i,j} = (4,2)$  and  $T_{k,l} = (10,4)$  on  $P$ , and they are scheduled rate-monotonically. Moreover, suppose that
- $T_{k,l}$  is the first subtask in the task  $T_k$  (i.e. it has no predecessors) and
  - The first three synchronization signals from the predecessor of  $T_{i,j}$  come at times 1, 2 and 3.

When are the first three jobs in  $T_{i,j}$  released on  $P$  ?

5 Attempt any **two** parts :

- Explain the VTCSMA algorithm for real-time communication with flowchart and by taking a suitable example.
- Differentiate between Real Time operating systems and general purpose operating systems. Explain the working of VRTX real time operating system.
- Discuss the various issues that arise in resource reservation. Describe any resource reservation protocol that can deal with these issues.

